



RS-Helios

A New Generation Of 32 Beams LiDAR
One-Stop Solution For Front Perception And
Near-Field Blind-Spot Detection



The RS-Helios is a new generation of 32 beams LiDAR that designed for robots, autonomous vehicles, V2X.

The RS-Helios-5515 adopts a design that arranges dense laser beams in the middle part of the FOV and sparse laser beams on both ends in order to obtain denser high-precision 3D point cloud of environment in front of the vehicle. Combined with a customized 70° ultra-wide vertical FOV tilting downward of 55° below horizon, it greatly reduces the near-field blind zone, and allows for both long-range perception and blind spots detection at the same time. This design will greatly facilitate a simpler vehicle sensor setup.

With an innovative new technonoly architecture, the size of the RS-Helios series is reduced by 29% compared to the RS-LiDAR-32.

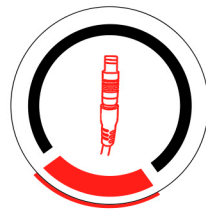
Product Advantages



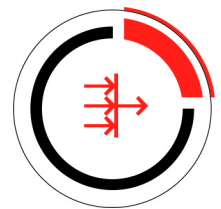
Customized FOV



-30°C
Temperature Resistance



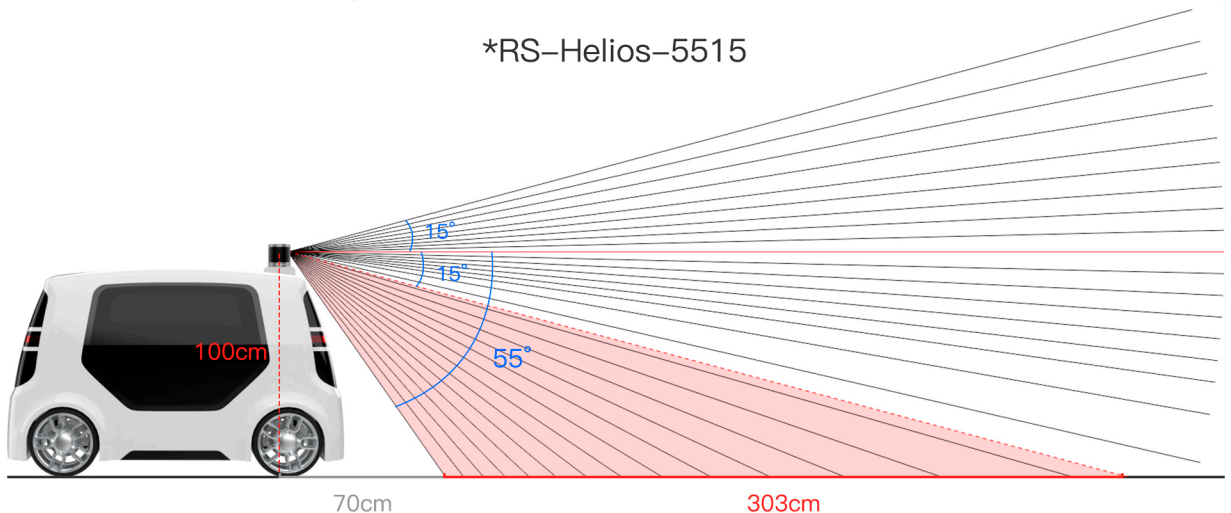
Automotive
Ethernet Connection



Anti-Interference of
Multi-LiDAR & Ambient Light

「Vertical FoV of 70°, 55° of FoV below horizon to elimilate blind zone」

*RS-Helios-5515



RoboSense / Suteng Innovation Technology Co., Ltd.

10-11/F, Block 3, Chongwen Garden, Nanshan IPark, 3370 Liuxian Avenue, Shenzhen, China / 0755-86325830 / service@robosense.cn



Q RoboSense LiDAR

www.robosense.ai

Sensor		
Version	RS-Helios-5515	RS-Helios-1615
Laser Beams	32	32
Laser Wavelength	905nm	905nm
Laser Safety	Class 1 eye safe	Class 1 eye safe
Range ¹	150m(80m@10% NIST)	150m(80m@10% NIST)
Blind Spot	≤0.1m	≤0.1m
Range Accuracy(Typical) ²	±2cm(1m to 100m) ±3cm(0.1m to 1m) ±3cm(100m to 150m)	±2cm(1m to 100m) ±3cm(0.1m to 1m) ±3cm(100m to 150m)
Horizontal FoV	360°	360°
Vertical FoV	70°(-55°~+15°)	31°(-16°~+15°)
Horizontal Resolution	0.2°/0.4° ⁵	0.2°/0.4° ⁵
Vertical Resolution	Up to 1.33°	1°
Frame Rate	10Hz/20 Hz	10Hz/20 Hz
Rotation Speed	600/1200rpm(10/20Hz)	600/1200rpm(10/20Hz)
Output		
Points Per Second	576,000pts/s(Single Return Mode) 1,152,000pts/s(Dual Return mode)	576,000pts/s(Single Return Mode) 1,152,000pts/s(Dual Return mode)
Ethernet Connection	100M Base T1	100M Base T1
Output Protocol	UDP packets over Ethernet	UDP packets over Ethernet
UDP Packet Content	Spatial Coordinates, Intensity, Timestamp, etc.	Spatial Coordinates, Intensity, Timestamp, etc.
Mechanical / Electrical / Operational		
Operating Voltage	9V – 32V	9V – 32V
Power Consumption ³	12W	12W
Weight(without cabling)	~1.0 kg	~1.0 kg
Dimension	φ100mm * H100 mm	φ100mm * H100 mm
Operating Temperature ⁴	-30°C ~ +60°C	-30°C ~ +60°C
Storage Temperature	-40°C ~ +85°C	-40°C ~ +85°C
Time Synchronization	\$GPRMC with 1PPS	\$GPRMC with 1PPS
Ingress Protection	IP67	IP67

* The above data is for mass-produced products only. Any samples, testing machine and other non-mass-produced versions may not be referred to this specification. If you have any questions, please contact RoboSense sales.

1. The product ranging performance may be affected by the environment conditions, including but not limited to factors such as ambient temperature and lighting.
2. The measurement target of accuracy measurement is a 50% NIST diffuse reflectance target. The test results may be affected by the environment, including but not limited to factors such as ambient temperature and target distance. The accuracy values are applicable to most channels, and there may be differences between some channels.
3. The product power consumption test is tested at a frame rate of 10Hz, and the results will be affected by the external environment, including but not limited to factors such as ambient temperature, target distance, target reflectivity, etc.
4. The operating temperature of the product may be affected by the external environment, including but not limited to factors such as solar radiation and airflow changes.
5. The corresponding operating frequency of 0.1°/0.2°/0.4° is 5Hz/10Hz/20Hz.

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